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| Team Id | PNT2022TMID43466 |
| Project Name | Emerging Methods For Early Detection OF Forest FIres |

EMERGING METHODS FOR EARLY DETECTION OF FOREST FIRES Team list

LITERATURE SURVEY:

1. Surapong Surit, Watchara Chatwiriya [8] proposed a method to detect fire by smoke detection in video. This approach is based on digital image processing approach with static and dynamic characteristic analysis. The proposed method is composed of following steps, the first is to detect the area of change in the current input frame in comparison with the background image, the second step is to locate regions of interest (ROIs) by connected component algorithm, the area of ROI is calculated by convex hull algorithm and segments the area of change from image, the third step is to calculate static and dynamic characteristics, using this result we decide whether the object detected is the smoke or not. The result shows that this method accurately detects fire smoke.Surapong Surit, Watchara Chatwiriya [8] proposed a method to detect fire by smoke detection in video. This approach is based on digital image processing approach with static and dynamic characteristic analysis. The proposed method is composed of following steps, the first is to detect the area of change in the current input frame in comparison with the background image, the second step is to locate regions of interest (ROIs) by connected component algorithm, the area of ROI is calculated by convex hull algorithm and segments the area of change from image, the third step is to calculate static and dynamic characteristics, using this result we decide whether the object detected is the smoke or not. The result shows that this method accurately detects fire smoke.

2. P. Piccinini, S. Calderara, and R. Cucchiara [2] proposed a method based on the wavelet model and a color model of the smoke. The proposed method exploits two features: the variation of energy in wavelet model and a color model of the smoke. Smoke is detected based on the decrease of energy ratio in wavelet domain between background and current. The deviation of the current pixel color is measured by the color model. Bayesian classifier is used to combine these two features to detect smoke

3. Osman Gunay and Habiboglu [4] proposed a system based on Covariance Descriptors, Color Models, and SVM Classifier. This system uses video data. Spatio-temporal Covariance Matrix (2011) [13] is used in this system which divides the video data into temporal blocks and computes covariance features. The fire is detected using this feature. SVM Classifier is used to filer fire and fire-like regions. This system supports only for clear data not for blur data

. 4. Hamed Adab [6] proposed another system which is based on Indexing. GIS techniques and remote sensing [10] provides further assistance. The indexing may be structural fire index, Fire risk index, Hybrid fire index. Depending on the geographical condition of the area the indexing differs. Validations of indices are based on hot spot data. Structural fire indices show static information and it does not change over short time span and used to predict the risk in advance. Fire risk index changes as the vegetation or climate changes. Hybrid index is a combination of Structure and Fire index. The disadvantage of this indexing is that way of combining

5. Celik (2007) [3] proposed a generic model for fire and smoke detection without the use of sensors [15]. Fuzzy based approach is used in this system. Color models such as YCbCr, HSV are used for fire and smoke detection. The fire is detected using YCbCr color model samples because it distinguishes luminance and chrominance. Y, Cb, Cr color channels are separated from RGB input image. A pixel is more likely a fire pixel if intensity of Y channel is greater than channel Cb and Cr.

6. Cheng (2011) [5] proposed a fire detection system based on Neural Network; here neural network is used in detection information for temperature, CO concentration, and smoke density to determine probability of three representative fire conditions. RBF neuron structure is used, the information regarding temperature, CO concentration, and smoke density are collected and data fusion is used to generate fire signal decision. The detectors have continuous analog outputs, when detection limit is exceeded the hardware circuit sends a local fire indication to fusion center, this force the system detectors to generate final decision. Single-sensor detector is used to generate the final decision.

7. Paulo Vinicius Koerich Borges [11] proposed a fire detection method based on probabilistic method and classification. Computer vision based approach is used in this approach. Though this approach is used surveillance it is also used to automatic video classification for retrieval of fire catastrophes in databases of newscast content. There are large variations in fire and background characteristics depending on the video instance. The proposed method observes the frame-to-frame changes of low-level features describing potential fire regions. These features include color, area size, surface coarseness, boundary roughness, and skewness within estimated fire regions. Bayes classifier [12] is used for fire recognition. In addition, apriori [12] knowledge of fire events captured in videos is used to significantly improve the results.

8. Akshata & Bhosale [7] proposed another method where Local Binary Pattern acts as a base for fire detection and Wavelet Decomposition is used to detect fire. Pixel level analysis is required in this method. This method uses YCbCr color model to detect fire. Detection is based on three phase. The first phase involves segmentation of image using LBP. LBP is a texture operator whose value is computed using image ’ s center and neighboring pixel values. Further accuracy is improved using Wavelet Transform and complicated data is classified using this approach. 2D Discrete Wavelet Transform is used for decomposition in this system. 2 images should be used as input and the sub bands of every image are compared with the other, if sub bands are equal the images are same else different.

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